

# Linear Systems and Signals

## Finding the impulse response

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# Learning objectives

The learning objective for this section is:

- find the impulse response of a DT system from an input-output formula



# Impulse response and convolution

We have the convolution formula:

$$y[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k] \quad (1)$$

$$= \sum_{k=-\infty}^{\infty} h[k]x[n-k] \quad (2)$$

*Handwritten notes:*  
 $\delta[n-k]$  is a system that delays its input by  $k$ .  
 a system w/ impulse response

How do we use a given input/output formula to write down  $h[n]$ ?

Easy case: if  $y[n]$  is already a linear combination of  $x[n-k]$ 's...

$$y[n] = 3x[n] - 2x[n-1] - x[n-3] \quad (3)$$

$$h[n] = 3\delta[n] - 2\delta[n-1] - \delta[n-3] \quad (4)$$

*Handwritten note:* replace  $x$  with  $\delta$



# A general approach

**Goal:** try to rewrite  $y[n]$  as a linear combination of delayed versions of  $x[n]$ . Then  $h[k]$  is the coefficient of  $x[n - k]$ . Let's try an example with *recursion*:

$$y[n] - \alpha y[n - 1] = x[n] \quad (5)$$

$$y[n] = \alpha y[n - 1] + x[n] \quad (6)$$

$$= \alpha^2 y[n - 2] + \alpha x[n - 1] + x[n] \quad (7)$$

$$= \alpha^3 y[n - 3] + \alpha^2 x[n - 2] + \alpha x[n - 1] + x[n] \quad (8)$$

$$= \sum_{k=0}^{\infty} \alpha^k x[n - k] \quad (9)$$

$$h[n] = \alpha^n \text{ for } n \geq 0$$

So  $h[n] = \alpha^n$  for  $n \geq 0$  and 0 otherwise. Another way to write this is  $h[n] = \alpha^n u[n]$ .



# Try some yourself

## Problem

Find the impulse response from the following input-output relations:

$$y[n] + \frac{1}{2}y[n-1] - \frac{1}{4}y[n-2] = x[n]$$

$$y[n] = 4x[n+1] - 2x[n-2] + 4x[n-4]$$

$$y[n] = \frac{1}{3}y[n-2] + x[n-1]$$

$$y[n] = \sum_{k=0}^{\infty} x[n-k]$$

