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(you can call me "Mike")

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Physics 194 - Lecture 7

Welcome!

Have a question during class? Please ask it right away, even if it means interrupting in the middle of a thought. I want you to!

Agenda

- Mathematical analysis of simple circuits
- Power
- Intro to the magnetic interaction

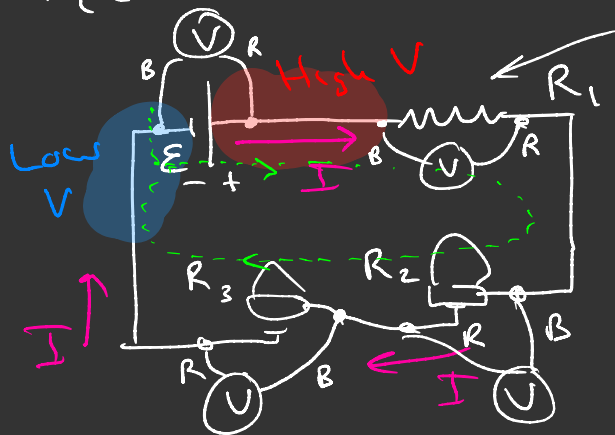
Class

starts

@2:15 pm

What you learned from using a voltmeter to analyze a circuit...

$$\mathcal{E} = qV$$



Resistor

A battery's EMF (electromotive force) is how "strong" the battery is. More or less how much energy it gives each charge that passes through it.

$$\Delta V$$

Potential difference

$$1) \Delta V_{\mathcal{E}} + \Delta V_{R_1} + \Delta V_{R_2} + \Delta V_{R_3} = 0$$

between 2 points in the circuit.

$$\begin{pmatrix} + \end{pmatrix} \quad \begin{pmatrix} - \end{pmatrix} \quad \begin{pmatrix} - \end{pmatrix} \quad \begin{pmatrix} - \end{pmatrix}$$

Kirchhoff's loop rule.

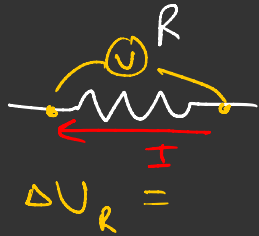
$$\sum \Delta V = 0$$

How do you represent a battery mathematically?



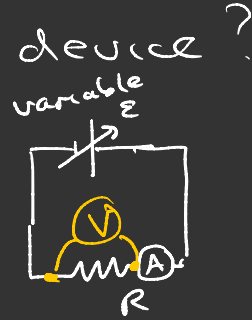
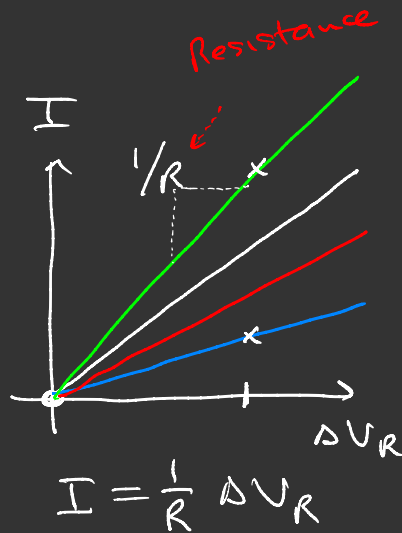
$$\Delta V_{\varepsilon} = \varepsilon$$

What about a resistive device?



$$\Delta V_R =$$

Ohm's
(law)



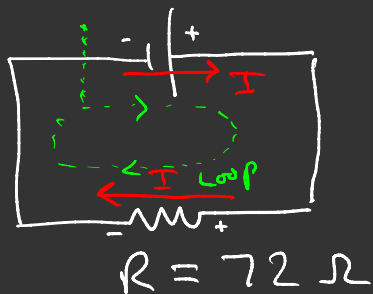
How does ΔV_R depend on I through it?

- Vary ε , that will vary ΔV_R .

$$\Delta V_{\varepsilon} + \Delta V_R = 0$$

$$\Delta V_R = IR \quad (V/A = \Omega, \text{ the "ohm"})$$

(V) (A) $\mathcal{E} = 120 \text{ V}$



$$\sum_{\text{loop}} \Delta V = 0$$

$$\Delta V_{\mathcal{E}} + \Delta V_R = 0$$

$$+\mathcal{E} - IR = 0$$

$$I = \frac{\mathcal{E}}{R} = \frac{120 \text{ V}}{72 \Omega} = 1.67 \text{ A}$$

Power

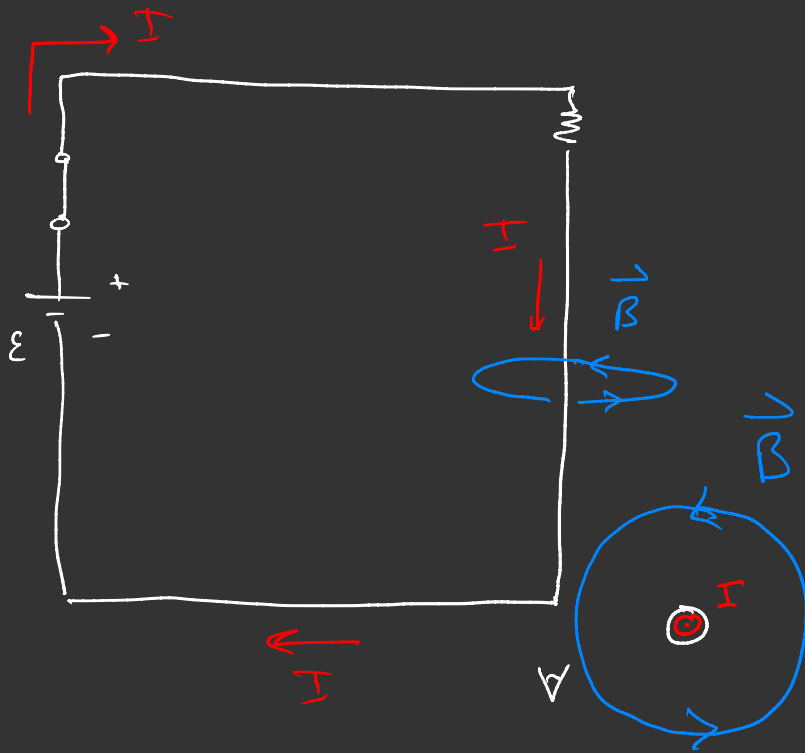
$$P = I \Delta V$$

(A) (V)

$$(W = J/s)$$

$$P_R = I_R \Delta V_R = (1.67 \text{ A})(120 \text{ V})$$

$$= 200 \text{ W}$$

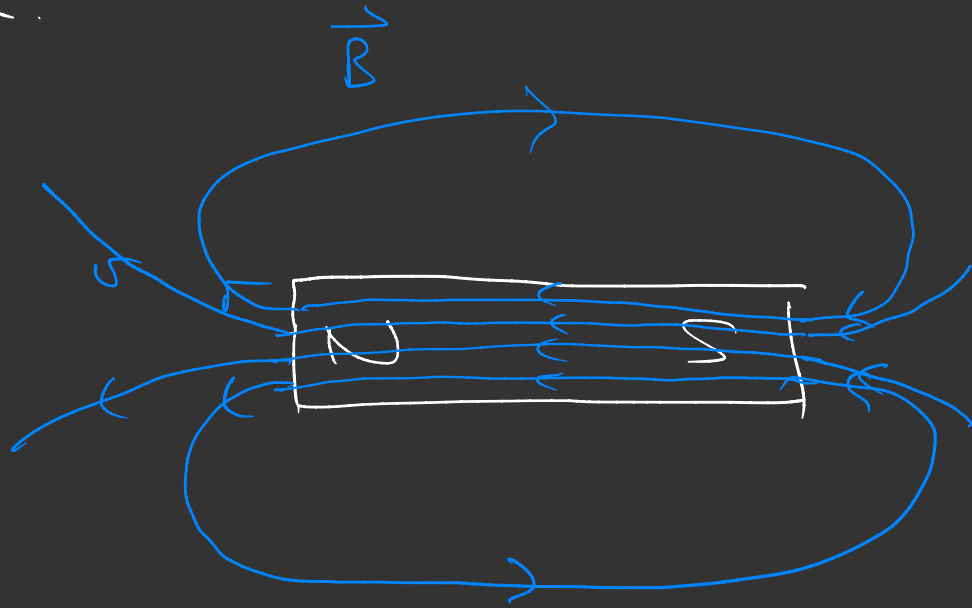
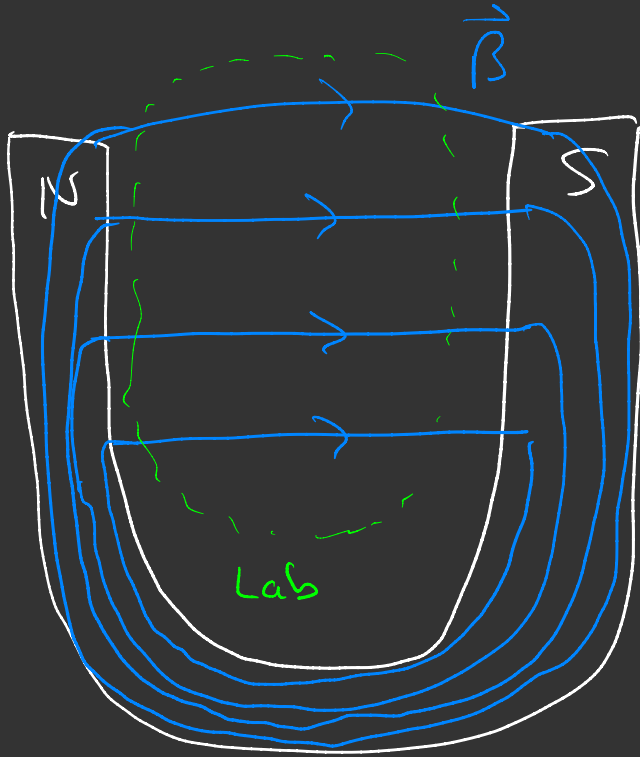


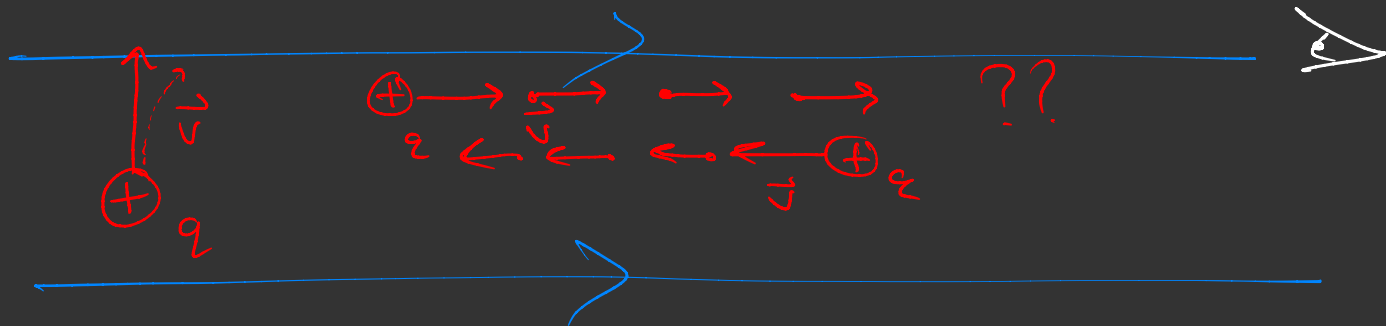
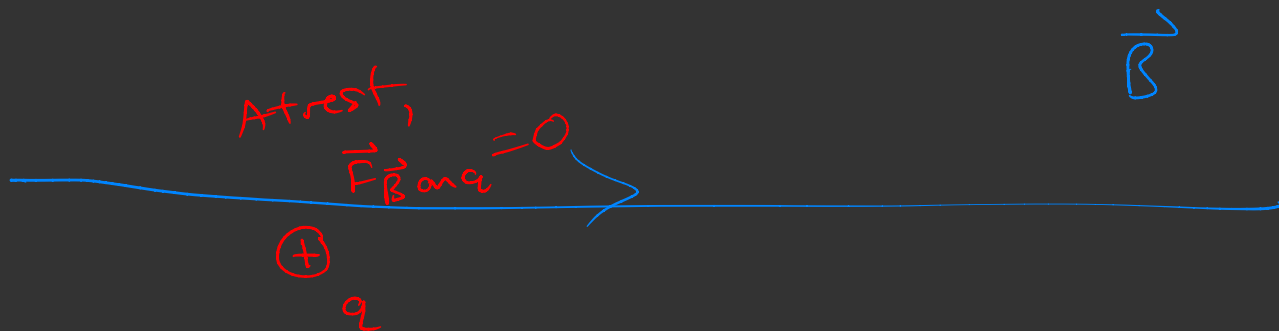
When the current
is flowing the compass
no longer pointed north!

Electric currents
produce a magnetic
field!

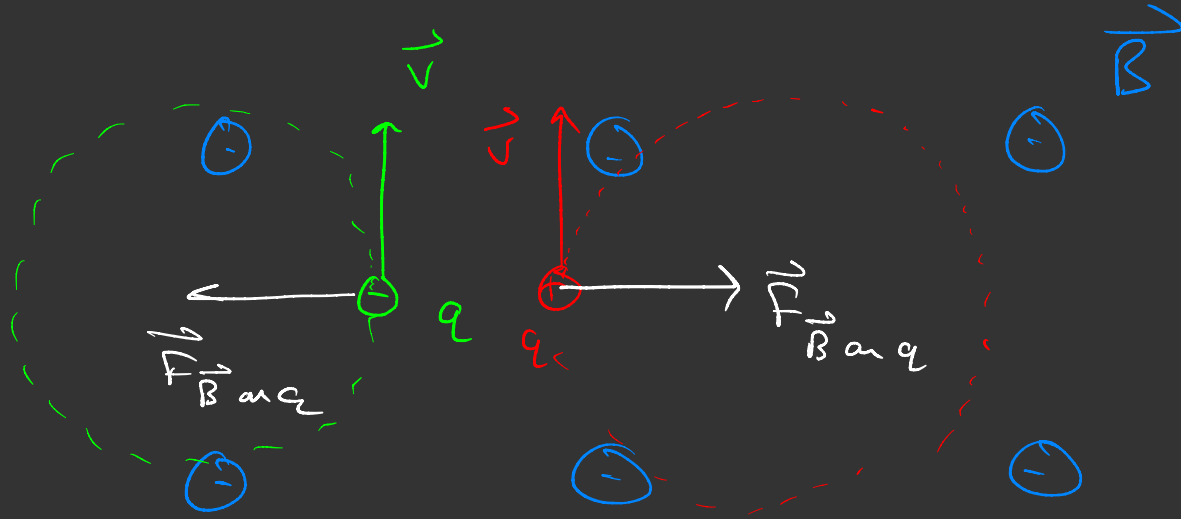
Fundamentally, a moving charged object produces
a magnetic field!

We need to start investigating the magnetic interaction.





Right hand rule



Fingers : \vec{B}
 Thumb : \vec{v}
 Palm : $\vec{F}_{\vec{B} \text{ on } \vec{q}}$

Knuckles : $\vec{F}_{\vec{B} \text{ on } \vec{q}}$